

1. Product Information

Product Name:JS-M710

Product Description:

JS-M710 is a compact, high performance, and low power consumption GNSS engine board.

It uses the chipset which can track up to 66 channels at a time and perform fast TTFF in weak signal environments.

JS-M710 is suitable for the following applications:

- Automotive navigation
- Personal positioning
- Fleet management
- Mobile phone navigation
- Marine navigation

Product Features:

- MediaTek high sensitivity solution
- Support 66-channel GPS
- Ultra low power consumption
- Fast TTFF at low signal level
- Built-in 12 multi-tone active interference canceller
- Free hybrid ephemeris prediction to achieve faster cold start
- Built-in data logger
- Built-in DC/DC converter to save power
- Up to 10 Hz update rate

- ± 1 ns high accuracy time pulse (1PPS)
- Capable of SBAS (WAAS, EGNOS, MSAS, GAGAN)
- Support Japan QZSS
- Indoor and outdoor multi-path detection and compensation
- Small form factor 10.1 * 9.7 * 2.5mm ± 0.2 mm
- SMD type with stamp holes
- RoHS compliant

Product Specifications

GPS Performance

| GPS Receiver | | |
|--------------------------------|-------------------------------|---|
| Chip | MediaTek MT3337 (Rom Version) | |
| Frequency | L1 1575.42MHz, C/A code | |
| Channels | Support 66 channels | |
| Update rate | 1Hz default, up to 10Hz | |
| Sensitivity | Tracking | -162dBm, up to -165dBm (with external LNA) |
| | Cold Start | -143.5dBm, up to -148dBm (with external LNA) |
| Acquisition Time | Hot start (Open Sky) | < 1s (typical) |
| | Hot start (Indoor) | < 30s |
| | Cold Start (Open Sky) | 32s (typical) without AGPS |
| | | < 15s (typical) with AGPS (hybrid ephemeris prediction) |
| Position Accuracy | Autonomous | 3m (2D RMS) |
| | SBAS | 2.5m (depends on accuracy of correction data) |
| Max. Altitude | < 50,000 m | |
| Max. Velocity | < 515 m/s | |
| Protocol Support | NMEA 0183 ver 4.01 | 9600 bps, 8 data bits, no parity, 1 stop bits (default) |
| | | 1Hz: GGA, GLL, GSA, GSV, RMC, VTG |
| Physical Characteristic | | |

| | |
|------------|--------------------------------|
| Type | 18 pin stamp holes |
| Dimensions | 10.1mm * 9.7 mm * 2.5mm ±0.2mm |

2. Technical Information

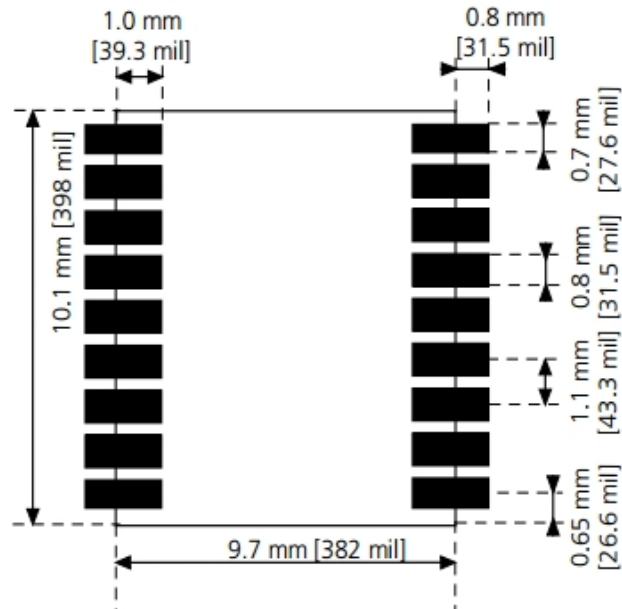
Module Pin Assignment

| | | | |
|----|-------|-----------|---|
| 10 | GND | VRESET | 9 |
| 11 | RF_IN | VCC | 8 |
| 12 | GND | NC | 7 |
| 13 | NC | V_BCKP | 6 |
| 14 | NC | NC | 5 |
| 15 | NC | TIMEPULSE | 4 |
| 16 | NC | RXD | 3 |
| 17 | NC | TXD | 2 |
| 18 | NC | GND | 1 |

| Pin NO. | Pin Name | I/O | Remark |
|---------|-----------|-----|--|
| 1. | GND | G | Ground. |
| 2. | TXD | O | Data Output |
| 3. | RXD | I | Data Input |
| 4. | TIMEPULSE | O | 1 Pulse per second |
| 5. | NC | N | Not connected |
| 6. | V_BCKP | PWR | Backup battery supply voltage |
| 7. | NC | N | Not connected |
| 8. | VCC | PWR | Main power supply to the engine board. |
| 9. | VRESET | I | Reset |
| 10. | GND | G | Ground. |
| 11. | RF_IN | RF | GPS antenna input |
| 12. | GND | G | Ground. |
| 13. | NC | N | Not connected |
| 14. | NC | N | Not connected |
| 15. | NC | N | Not connected |
| 16. | NC | N | Not connected |

| | | | |
|-----|----|---|---------------|
| 17. | NC | N | Not connected |
| 18. | NC | N | Not connected |

Dimensions



3. NMEA 0183 Protocol

The NMEA protocol is an ASCII-based protocol, Records start with a \$ and with carriage return/line feed. GPS specific messages all start with \$GPxxx where xxx is a three-letter identifier of the message data that follows. NMEA messages have a checksum, which allows detection of corrupted data transfers.

JS-M710 modules support the following NMEA-0183 messages: GGA, GLL,GSA, GSV, RMC and VTG.

Table 1: NMEA-0183 Output Messages

| NMEA Record | DESCRIPTION |
|-------------|--|
| GGA | Global positioning system fixed data |
| GLL | Geographic position—latitude/longitude |
| GSA | GNSS DOP and active satellites |
| GSV | GNSS satellites in view |

| | |
|-----|--|
| RMC | Recommended minimum specific GNSS data |
| VTG | Course over ground and ground speed |

GGA-Global Positioning System Fixed Data

Table 2 contains the values of the following example:

\$GPGGA,035148.000,2238.1641,N,11403.6682,E,2,12,0.83,115.1,M,-2.2,M,0000,0000*71

Table 2: GGA Data Format

| Name | Example | Units | Description |
|------------------------|------------|--------|-----------------------------------|
| Message ID | \$GPGGA | | GGA protocol header |
| UTC Position | 035148.000 | | hhmmss.sss |
| Latitude | 2238.1641 | | ddmm.mmmmm |
| N/S indicator | N | | N=north or S=south |
| Longitude | 11403.6682 | | ddmm.mmmmm |
| E/W Indicator | E | | E=east or W=west |
| Position Fix Indicator | 2 | | See Table 2-1 |
| Satellites Used | 12 | | Range 0 to 12 |
| HDOP | 0.83 | | Horizontal Dilution of Precision |
| MSL Altitude | 115.1 | meters | |
| Units | M | meters | |
| Geoids Separation | | meters | |
| Units | M | meters | |
| Age of Diff. Corr. | | second | Null fields when DGPS is not Used |
| Diff. Ref. Station ID | 0000 | | |
| Checksum | *18 | | |
| <CR> <LF> | | | End of message termination |

Table 2-1: Position Fix Indicators

| Value | Description |
|-------|------------------------------|
| 0 | Fix not available or invalid |
| 1 | GPS SPS Mode, fix valid |

| | |
|---|---------------------------------------|
| 2 | Differential GPS, SPS Mode, fix valid |
| 3 | GPS PPS Mode, fix valid |

GLL-Geographic Position – Latitude/Longitude

Table 3 contains the values of the following example:

\$GPGLL , 2238.1641, N,11403.6682,E,035148.000, A*2C.

Table 3: GLL Data Format

| Name | Example | Units | Description |
|---------------|------------|-------|----------------------------------|
| Message ID | \$GPGLL | | GLL protocol header |
| Latitude | 2238.1641 | | Ddmm.mmmmm |
| N/S Indicator | N | | N=north or S=south |
| Longitude | 11403.6682 | | ddmm.mmmmm |
| E/W Indicator | W | | E=east orW=west |
| UTC Position | 035148.000 | | Hhmmss.sss |
| Status | A | | A=data valid or V=data not valid |
| Checksum | *2C | | |
| <CR> <LF> | | | End of message termination |

GSA-GNSS DOP and Active Satellites

Table 4 contains the values of the following example:

\$GPGSA , A, 3, 07, 02, 26,27, 09, 04,15, , , , , , 1.8,1.0,1.5*33.

Table 4: GSA Data Format

| Name | Example | Units | Description |
|----------------|---------|-------|---------------------|
| Message ID | \$GPGSA | | GSA protocol header |
| Mode 1 | A | | See Table 4-2 |
| Mode 2 | 3 | | See Table 4-1 |
| Satellite Used | 07 | | Sv on Channel 1 |
| Satellite Used | 02 | | Sv on Channel 2 |
| ... | ... | | ... |

| | | | |
|----------------|-----|--|----------------------------------|
| Satellite Used | | | Sv on Channel 12 |
| PDOP | 1.8 | | Position Dilution of Precision |
| HDOP | 1.0 | | Horizontal Dilution of Precision |
| VDOP | 1.5 | | Vertical Dilution of Precision |
| Checksum | *33 | | |
| <CR> <LF> | | | End of message termination |

Table 4-1: Mode 1

| Value | Description |
|-------|-------------------|
| 1 | Fix not available |
| 2 | 2D |
| 3 | 3D |

Table 4-2: Mode 2

| Value | Description |
|-------|---|
| M | Manual-forced to operate in 2D or 3D mode |
| A | Automatic-allowed to automatically switch 2D/3D |

GSV-GNSS Satellites in View

Table 5 contains the values of the following example:

\$GPGSV , 2, 1, 07, 07, 79,048, 42, 02, 51,062, 43, 26, 36,256, 42, 27, 27, 138,42*71

\$GPGSV, 2, 2, 07, 09, 23,313, 42, 04, 19, 159, 41, 15,12,041, 42*41.

Table 5: GGA Data Format

| Name | Example | Units | Description |
|--------------------|---------|-------|--------------------------|
| Message ID | \$GPGSV | | GSV protocol header |
| Number of Message | 2 | | Range 1 to 3 |
| Message Number | 1 | | Range 1 to 3 |
| Satellites in View | 07 | | |
| Satellite ID | 07 | | Channel 1(Range 1 to 32) |

| | | | |
|--------------|-----|---------|---------------------------------------|
| Elevation | 79 | degrees | Channel 1(Maximum 90) |
| Azinmuth | 048 | degrees | Channel 1(True, Range 0 to 359) |
| SNR(C/NO) | 42 | dBHz | Range 0 to 99,null when not tracking |
| ... | | | ... |
| Satellite ID | 27 | | Channel 4(Range 1 to 32) |
| Elevation | 27 | degrees | Channel 4(Maximum 90) |
| Azimuth | 138 | degrees | Channel 4(True, Range 0 to 359) |
| SNR(C/NO) | 42 | dBHz | Range 0 to 99, null when not tracking |
| Checksum | *71 | | |
| <CR> <LF> | | | End of message termination |

Depending on the number of satellites tracked multiple messages of GSV data may be required

RMC-Recommended Minimum Specific GNSS Data

Table 6 contains the values of the following example:

\$GPRMC,035148.000,A,2238.1641,N,11403.6682,E,0.02,358.09,290713,,D*6F

Table 6: RMC Data Format

| Name | Example | Units | Description |
|-------------------|------------|---------|----------------------------------|
| Message ID | \$GPRMC | | RMC protocol header |
| UTS Position | 035148.000 | | hhmmss.sss |
| Status | A | | A=data valid or V=data not valid |
| Latitude | 2238.1641 | | ddmm.mmmmm |
| N/S Indicator | N | | N=north or S=south |
| Longitude | 11403.6682 | | Ddmm.mmmmm |
| E/W Indicator | E | | E=east orW=west |
| Speed Over Ground | 0.02 | Knots | |
| Course Over | 358.09 | Degrees | True |
| Ground | | | |
| Date | 290713 | | Dummy |

| | | | |
|--------------------|-----|---------|----------------------------|
| Magnetic variation | | Degrees | E=east or W=west |
| Checksum | *6F | | |
| <CR> <LF> | | | End of message termination |

VTG-Course Over Ground and Ground Speed

Table 7 contains the values of the following example:

\$GPVTG, 309.62, T, M, 0.13, N, 0.2, K*6E

Table 7: VTG Data Format

| Name | Example | Units | Description |
|------------|---------|---------|----------------------------|
| Message ID | \$GPVTG | | VTG protocol header |
| Course | 309.62 | Degrees | Measured heading |
| Reference | T | | True |
| Course | | Degrees | Measured heading |
| Reference | M | | Magnetic |
| Speed | 0.13 | Knots | Measured horizontal speed |
| Units | N | | Knots |
| Speed | 0.2 | Km/hr | Measured horizontal speed |
| Units | K | | Kilometer per hour |
| Checksum | K | | Kilometer per hour |
| Date | *6E | | |
| <CR> <LF> | | | End of message termination |